

# **ADC0831-N/ADC0832-N/ADC0834-N/ADC0838-N 8-Bit Serial I/O A/D Converters with Multiplexer Options**

**Check for Samples: [ADC0831-N](http://www.ti.com/product/adc0831-n#samples), [ADC0832-N](http://www.ti.com/product/adc0832-n#samples), [ADC0834-N](http://www.ti.com/product/adc0834-n#samples), [ADC0838-N](http://www.ti.com/product/adc0838-n#samples)**

- **<sup>2</sup>• TI MICROWIRE Compatible—Direct Interface to • Resolution: 8 Bits COPS Family Processors • Total Unadjusted Error: ±½ LSB and ±1 LSB**
- **Easy Interface to All Microprocessors, or •** Single Supply: 5  $V_{DC}$ **Operates "Stand-Alone"**
- **• Operates** Ratiometrically or with 5  $V_{DC}$  Voltage **• Conversion Time:** 32 µ**s Reference**
- **• No Zero or Full-Scale Adjust Required DESCRIPTION**
- 
- 
- 
- 
- 
- **• 0.3** well as channel assignment. **in. Standard Width, 8-, 14- or 20-Pin PDIP**
- 
- 

## **<sup>1</sup>FEATURES KEY SPECIFICATIONS**

- 
- 
- 
- **• Low Power: 15 mW**
- 

**• 2-, 4- or 8-Channel Multiplexer Options with** The ADC0831 series are 8-bit successive **Address Logic** approximation A/D converters with a serial I/O and **Shunt Regulator Allows Operation with High** configurable input multiplexers with up to 8 channels.<br>**Voltage Supplies**<br>**•** The serial I/O is configured to comply with the TI The serial I/O is configured to comply with the TI **Voltage Supplies** MICROWIRE serial data exchange standard for easy **• 0V to 5V Input Range with Single 5V Power** interface to the COPS family of processors, and can **Supply** interface with standard shift registers or μPs.

**•• Remote Operation with Serial Digital Data Link**<br>**•• The 2-, 4- or 8-channel multiplexers are software**<br>**•• configured** for single-ended or differential inputs as **• TTL/MOS Input/Output Compatible** configured for single-ended or differential inputs as

**Package Package The differential analog voltage input allows increasing • 20 Pin PLCC Package (ADC0838-N Only)** the common-mode rejection and offsetting the analog zero input voltage value. In addition, the voltage **• SOIC Package** reference input can be adjusted to allow encoding any smaller analog voltage span to the full 8 bits of resolution.

## **Typical Application**



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### **Connection Diagrams**



#### **Figure 1. ADC0838-N 8-Channel Mux SOIC/PDIP Package (DW or NFH) Top View**







COM internally connected to A GND Top View





**Figure 4. ADC0831-N Single Differential Input PDIP Package (P) Top View**



COM internally connected to GND.  $V_{REF}$  internally connected to  $V_{CC}$ . Top View

#### **Figure 5. ADC0832-N 2-Channel MUX PDIP Package (P) Top View**







**Figure 7. ADC0838-N 8-Channel MUX PLCC Package (FN)**



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

### **Absolute Maximum Ratings(1)(2)(3)**



(1) All voltages are measured with respect to the ground plugs.

(2) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. DC and AC electrical specifications do not apply when operating the device beyond its specified operating conditions.

(3) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/Distributors for availability and specifications.

(4) Internal zener diodes (6.3 to 8.5V) are connected from V+ to GND and V<sub>CC</sub> to GND. The zener at V+ can operate as a shunt regulator and is connected to  $V_{CC}$  via a conventional diode. Since the zener voltage equals the A/D's breakdown voltage, the diode insures that V<sub>CC</sub> will be below breakdown when the device is powered from V+. Functionality is therefore ensured for V+ operation even though the resultant voltage at  $V_{CC}$  may exceed the specified Absolute Max of 6.5V. It is recommended that a resistor be used to limit the max current into V+. (See [Figure](#page-17-0) 24 in Functional Description)

(5) When the input voltage  $(V_{\text{IN}})$  at any pin exceeds the power supply rails ( $V_{\text{IN}}$  < V<sup>-</sup> or  $V_{\text{IN}}$  > V<sup>+</sup>) the absolute value of current at that pin should be limited to 5 mA or less. The 20 mA package input current limits the number of pins that can exceed the power supply boundaries with a 5 mA current limit to four.

(6) Human body model, 100 pF discharged through a 1.5 kΩ resistor.

### **Operating Ratings(1)(2)**



(1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. DC and AC electrical specifications do not apply when operating the device beyond its specified operating conditions.

(2) All voltages are measured with respect to the ground plugs.



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### **Converter and Multiplexer Electrical Characteristics**

The following specifications apply for  $V_{CC} = V_+ = V_{REF} = 5V$ ,  $V_{REF} \leq V_{CC} + 0.1V$ ,  $T_A = T_j = 25^{\circ}C$ , and  $f_{CLK} = 250$  kHz unless **otherwise specified. Boldface limits apply from**  $T_{MIN}$  **to**  $T_{MAX}$ **.** 



(1) Typicals are at 25°C and represent most likely parametric norm.

(2) Tested limits are ensured to TI's AOQL (Average Outgoing Quality Level).

(3) Ensured but not 100% production tested. These limits are not used to calculate outgoing quality levels.

(4) Total unadjusted error includes offset, full-scale, linearity, and multiplexer errors.

(5) Cannot be tested for ADC0832-N.

(6) For V<sub>IN</sub>(−) ≥ V<sub>IN</sub>(+) the digital output code will be 0000 0000. Two on-chip diodes are tied to each analog input (see [Functional](#page-11-0) Block [Diagram](#page-11-0)) which will forward conduct for analog input voltages one diode drop below ground or one diode drop greater than the  $V_{CC}$ supply. Be careful, during testing at low  $V_{CC}$  levels (4.5V), as high level analog inputs (5V) can cause this input diode to conduct—especially at elevated temperatures, and cause errors for analog inputs near full-scale. The spec allows 50 mV forward bias of either diode. This means that as long as the analog V<sub>IN</sub> or V<sub>REF</sub> does not exceed the supply voltage by more than 50 mV, the output code will be correct. To achieve an absolute 0  $V_{DC}$  to 5  $V_{DC}$  input voltage range will therefore require a minimum supply voltage of 4.950  $V_{DC}$  over temperature variations, initial tolerance and loading.

(7) Internal zener diodes (6.3 to 8.5V) are connected from V+ to GND and V<sub>CC</sub> to GND. The zener at V+ can operate as a shunt regulator and is connected to  $V_{CC}$  via a conventional diode. Since the zener voltage equals the A/D's breakdown voltage, the diode insures that  $V_{CC}$  will be below breakdown when the device is powered from V+. Functionality is therefore ensured for V+ operation even though the resultant voltage at  $V_{CC}$  may exceed the specified Absolute Max of 6.5V. It is recommended that a resistor be used to limit the max current into V+. (See [Figure](#page-17-0) 24 in Functional Description)

(8) Leakage current is measured with the clock not switching.



### **Converter and Multiplexer Electrical Characteristics (continued)**

The following specifications apply for V<sub>CC</sub> = V+ = V<sub>REF</sub> = 5V, V<sub>REF</sub> ≤ V<sub>CC</sub> +0.1V, T<sub>A</sub> = T<sub>j</sub> = 25°C, and f<sub>CLK</sub> = 250 kHz unless otherwise specified. **Boldface limits apply from TMIN to TMAX.**



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### **AC Characteristics**

The following specifications apply for  $V_{CC} = 5V$ ,  $t_r = t_f = 20$  ns and 25°C unless otherwise specified.



(1) Typicals are at 25°C and represent most likely parametric norm.

(2) Tested limits are ensured to TI's AOQL (Average Outgoing Quality Level).

Ensured but not 100% production tested. These limits are not used to calculate outgoing quality levels.

(4) A 40% to 60% clock duty cycle range insures proper operation at all clock frequencies. In the case that an available clock has a duty cycle outside of these limits, the minimum, time the clock is high or the minimum time the clock is low must be at least 1 μs. The maximum time the clock can be high is 60 μs. The clock can be stopped when low so long as the analog input voltage remains stable.

(5) Since data, MSB first, is the output of the comparator used in the successive approximation loop, an additional delay is built in (see [ADC0838-N](#page-11-0) Functional Block Diagram) to allow for comparator response time.

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### **EXAS NSTRUMENTS**

<span id="page-6-0"></span>

**Typical Performance Characteristics**







fclk (kHz)



**Figure 12. Figure 13.**



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### **Leakage Current Test Circuit**



### <span id="page-7-0"></span>**TRI-STATE Test Circuits and Waveforms**









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### <span id="page-8-0"></span>**Timing Diagrams**





 $(MSB)$ 

MUX SETTLING<br>TIME

 $\frac{0}{\text{(LSB)}}$ 

7<br>(MSB)



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**Figure 20. ADC0834-N Timing**

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\*Make sure clock edge  $\#18$  clocks in the LSB before  $\overline{\text{SE}}$  is taken low

**Figure 21. ADC0838-N Timing**

**EXAS** 

Instruments



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### <span id="page-11-0"></span>**ADC0838-N Functional Block Diagram**



\*Some of these functions/pins are not available with other options.

Note 1: For the ADC0834-N, D1 is input directly to the D input of SELECT 1. SELECT 0 is forced to a "1". For the ADC0832-N, DI is input directly to the DI input of ODD/SIGN. SELECT 0 is forced to a "0" and SELECT 1 is forced to a "1".



### **Functional Description**

### **Multiplexer Addressing**

The design of these converters utilizes a sample-data comparator structure which provides for a differential analog input to be converted by a successive approximation routine.

The actual voltage converted is always the difference between an assigned "+" input terminal and a "−" input terminal. The polarity of each input terminal of the pair being converted indicates which line the converter expects to be the most positive. If the assigned "+" input is less than the "−" input the converter responds with an all zeros output code.

A unique input multiplexing scheme has been utilized to provide multiple analog channels with softwareconfigurable single-ended, differential, or a new pseudo-differential option which will convert the difference between the voltage at any analog input and a common terminal. The analog signal conditioning required in transducer-based data acquisition systems is significantly simplified with this type of input flexibility. One converter package can now handle ground referenced inputs and true differential inputs as well as signals with some arbitrary reference voltage.

A particular input configuration is assigned during the MUX addressing sequence, prior to the start of a conversion. The MUX address selects which of the analog inputs are to be enabled and whether this input is single-ended or differential. In the differential case, it also assigns the polarity of the channels. Differential inputs are restricted to adjacent channel pairs. For example channel 0 and channel 1 may be selected as a different pair but channel 0 or 1 cannot act differentially with any other channel. In addition to selecting differential mode the sign may also be selected. Channel 0 may be selected as the positive input and channel 1 as the negative input or vice versa. This programmability is best illustrated by the MUX addressing codes shown in the following tables for the various product options.

The MUX address is shifted into the converter via the DI line. Because the ADC0831-N contains only one differential input channel with a fixed polarity assignment, it does not require addressing.

The common input line on the ADC0838-N can be used as a pseudo-differential input. In this mode, the voltage on this pin is treated as the "−" input for any of the other input channels. This voltage does not have to be analog ground; it can be any reference potential which is common to all of the inputs. This feature is most useful in single-supply application where the analog circuitry may be biased up to a potential other than ground and the output signals are all referred to this potential.











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### **Table 3. MUX Addressing: ADC0838-N Differential MUX Mode**



### **Table 4. MUX Addressing: ADC0834-N Single-Ended MUX Mode**



### **Table 5. MUX Addressing: ADC0834-N Differential MUX Mode**



#### **Table 6. MUX Addressing: ADC0832-N Single-Ended MUX Mode**



#### **Table 7. MUX Addressing: ADC0832-N Differential MUX Mode**



Since the input configuration is under software control, it can be modified, as required, at each conversion. A channel can be treated as a single-ended, ground referenced input for one conversion; then it can be reconfigured as part of a differential channel for another conversion. [Figure](#page-14-0) 22 illustrates the input flexibility which can be achieved.

The analog input voltages for each channel can range from 50 mV below ground to 50 mV above  $V_{CC}$  (typically 5V) without degrading conversion accuracy.

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### **THE DIGITAL INTERFACE**

A most important characteristic of these converters is their serial data link with the controlling processor. Using a serial communication format offers two very significant system improvements; it allows more function to be included in the converter package with no increase in package size and it can eliminate the transmission of low level analog signals by locating the converter right at the analog sensor; transmitting highly noise immune digital data back to the host processor.

To understand the operation of these converters it is best to refer to the Timing [Diagrams](#page-8-0) and [Functional](#page-11-0) Block [Diagram](#page-11-0) and to follow a complete conversion sequence. For clarity a separate diagram is shown of each device.

1. A conversion is initiated by first pulling the  $\overline{CS}$  (chip select) line low. This line must be held low for the entire conversion. The converter is now waiting for a start bit and its MUX assignment word.

2. A clock is then generated by the processor (if not provided continuously) and output to the A/D clock input.



**Figure 22. Analog Input Multiplexer Options for the ADC0838-N**

<span id="page-14-0"></span>3. On each rising edge of the clock the status of the data in (DI) line is clocked into the MUX address shift register. The start bit is the first logic "1" that appears on this line (all leading zeros are ignored). Following the start bit the converter expects the next 2 to 4 bits to be the MUX assignment word.

4. When the start bit has been shifted into the start location of the MUX register, the input channel has been assigned and a conversion is about to begin. An interval of ½ clock period (where nothing happens) is automatically inserted to allow the selected MUX channel to settle. The SAR status line goes high at this time to signal that a conversion is now in progress and the DI line is disabled (it no longer accepts data).

5. The data out (DO) line now comes out of TRI-STATE and provides a leading zero for this one clock period of MUX settling time.

6. When the conversion begins, the output of the SAR comparator, which indicates whether the analog input is greater than (high) or less than (low) each successive voltage from the internal resistor ladder, appears at the DO line on each falling edge of the clock. This data is the result of the conversion being shifted out (with the MSB coming first) and can be read by the processor immediately.



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7. After 8 clock periods the conversion is completed. The SAR status line returns low to indicate this ½ clock cycle later.

8. If the programmer prefers, the data can be provided in an LSB first format [this makes use of the shift enable (SE) control line]. All 8 bits of the result are stored in an output shift register. On devices which do not include the SE control line, the data, LSB first, is automatically shifted out the DO line, after the MSB first data stream. The DO line then goes low and stays low until CS is returned high. On the ADC0838-N the SE line is brought out and if held high, the value of the LSB remains valid on the DO line. When SE is forced low, the data is then clocked out LSB first. The ADC0831-N is an exception in that its data is only output in MSB first format.

9. All internal registers are cleared when the CS line is high. If another conversion is desired, CS must make a high to low transition followed by address information.

The DI and DO lines can be tied together and controlled through a bidirectional processor I/O bit with one wire. This is possible because the DI input is only "looked-at" during the MUX addressing interval while the DO line is still in a high impedance state.

#### **Reference Considerations**

The voltage applied to the reference input to these converters defines the voltage span of the analog input (the difference between  $V_{IN(MAX)}$  and  $V_{IN(MIN)}$ ) over which the 256 possible output codes apply. The devices can be used in either ratiometric applications or in systems requiring absolute accuracy. The reference pin must be connected to a voltage source capable of driving the reference input resistance of typically 3.5 kΩ. This pin is the top of a resistor divider string used for the successive approximation conversion.

In a ratiometric system, the analog input voltage is proportional to the voltage used for the A/D reference. This voltage is typically the system power supply, so the  $V_{REF}$  pin can be tied to  $V_{CC}$  (done internally on the ADC0832-N). This technique relaxes the stability requirements of the system reference as the analog input and A/D reference move together maintaining the same output code for a given input condition.

For absolute accuracy, where the analog input varies between very specific voltage limits, the reference pin can be biased with a time and temperature stable voltage source. The LM385 and LM336 reference diodes are good low current devices to use with these converters.

The maximum value of the reference is limited to the  $V_{CC}$  supply voltage. The minimum value, however, can be quite small (see Typical Performance [Characteristics\)](#page-6-0) to allow direct conversions of transducer outputs providing less than a 5V output span. Particular care must be taken with regard to noise pickup, circuit layout and system error voltage sources when operating with a reduced span due to the increased sensitivity of the converter (1 LSB equals  $V_{REF}/256$ ).





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### **The Analog Inputs**

The most important feature of these converters is that they can be located right at the analog signal source and through just a few wires can communicate with a controlling processor with a highly noise immune serial bit stream. This in itself greatly minimizes circuitry to maintain analog signal accuracy which otherwise is most susceptible to noise pickup. However, a few words are in order with regard to the analog inputs should the input be noisy to begin with or possibly riding on a large common-mode voltage.

The differential input of these converters actually reduces the effects of common-mode input noise, a signal common to both selected "+" and "−" inputs for a conversion (60 Hz is most typical). The time interval between sampling the "+" input and then the "−" input is 1/2 of a clock period. The change in the common-mode voltage during this short time interval can cause conversion errors. For a sinusoidal common-mode signal this error is:

$$
V_{error}(max) = V_{PEAK}(2\pi f_{CM}) \left(\frac{0.5}{f_{CLK}}\right)
$$

where

- $\bullet$  f<sub>CM</sub> is the frequency of the common-mode signal
- $V_{PEAK}$  is its peak voltage value
- $f_{\text{Cl K}}$ , is the A/D clock frequency (1)

For a 60 Hz common-mode signal to generate a ¼ LSB error (≈5 mV) with the converter running at 250 kHz, its peak value would have to be 6.63V which would be larger than allowed as it exceeds the maximum analog input limits.

Due to the sampling nature of the analog inputs short spikes of current enter the "+" input and exit the "−" input at the clock edges during the actual conversion. These currents decay rapidly and do not cause errors as the internal comparator is strobed at the end of a clock period. Bypass capacitors at the inputs will average these currents and cause an effective DC current to flow through the output resistance of the analog signal source. Bypass capacitors should not be used if the source resistance is greater than 1 kΩ.

This source resistance limitation is important with regard to the DC leakage currents of input multiplexer as well. The worst-case leakage current of  $\pm 1$  µA over temperature will create a 1 mV input error with a 1 kΩ source resistance. An op amp RC active low pass filter can provide both impedance buffering and noise filtering should a high impedance signal source be required.

### **Optional Adjustments**

#### **Zero Error**

The zero of the A/D does not require adjustment. If the minimum analog input voltage value,  $V_{IN(MIN)}$ , is not ground a zero offset can be done. The converter can be made to output 0000 0000 digital code for this minimum input voltage by biasing any V<sub>IN</sub> (−) input at this V<sub>IN(MIN)</sub> value. This utilizes the differential mode operation of the A/D.

The zero error of the A/D converter relates to the location of the first riser of the transfer function and can be measured by grounding the V<sub>IN</sub>(−) input and applying a small magnitude positive voltage to the V<sub>IN</sub>(+) input. Zero error is the difference between the actual DC input voltage which is necessary to just cause an output digital code transition from 0000 0000 to 0000 0001 and the ideal  $\frac{1}{2}$  LSB value ( $\frac{1}{2}$  LSB=9.8 mV for V<sub>REF</sub>=5.000 V<sub>DC</sub>).

#### **Full-Scale**

The full-scale adjustment can be made by applying a differential input voltage which is 1 ½ LSB down from the desired analog full-scale voltage range and then adjusting the magnitude of the  $V_{REF}$  input (or  $V_{CC}$  for the ADC0832) for a digital output code which is just changing from 1111 1110 to 1111 1111.

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#### **Adjusting for an Arbitrary Analog Input Voltage Range**

If the analog zero voltage of the A/D is shifted away from ground (for example, to accommodate an analog input signal which does not go to ground), this new zero reference should be properly adjusted first. A  $V_{\text{IN}}$  (+) voltage which equals this desired zero reference plus  $\frac{1}{2}$  LSB (where the LSB is calculated for the desired analog span, using 1 LSB= analog span/256) is applied to selected "+" input and the zero reference voltage at the corresponding "−" input should then be adjusted to just obtain the  $00<sub>HEX</sub>$  to  $01<sub>HEX</sub>$  code transition.

The full-scale adjustment should be made [with the proper V<sub>IN</sub>(−) voltage applied] by forcing a voltage to the  $V_{\text{IN}}(+)$  input which is given by:

$$
V_{IN} \left( + \right) \text{fs adj} = V_{MAX} - 1.5 \left[ \frac{\left( V_{MAX} - V_{MIN} \right)}{256} \right]
$$

where

- $V_{MAX}$  = the high end of the analog input range
	- $V_{\text{MIN}}$  = the low end (the offset zero) of the analog range. (Both are ground referenced.) (2)

The V<sub>REF</sub> (or V<sub>CC</sub>) voltage is then adjusted to provide a code change from FE<sub>HEX</sub> to FF<sub>HEX</sub>. This completes the adjustment procedure.

### **Power Supply**

A unique feature of the ADC0838-N and ADC0834-N is the inclusion of a zener diode connected from the V<sup>+</sup> terminal to ground which also connects to the  $V_{CC}$  terminal (which is the actual converter supply) through a silicon diode, as shown in [Figure](#page-17-0)  $24^{(1)}$ .



**Figure 24. An On-Chip Shunt Regulator Diode**

<span id="page-17-0"></span>This zener is intended for use as a shunt voltage regulator to eliminate the need for any additional regulating components. This is most desirable if the converter is to be remotely located from the system power source. [Figure](#page-18-0) 25 and [Figure](#page-18-1) 27 illustrate two useful applications of this on-board zener when an external transistor can be afforded.

An important use of the interconnecting diode between V<sup>+</sup> and V<sub>CC</sub> is shown in [Figure](#page-18-3) 26 and Figure 28. Here, this diode is used as a rectifier to allow the  $V_{CC}$  supply for the converter to be derived from the clock. The low current requirements of the A/D and the relatively high clock frequencies used (typically in the range of 10k–400 kHz) allows using the small value filter capacitor shown to keep the ripple on the V<sub>CC</sub> line to well under  $\frac{1}{4}$  of an LSB. The shunt zener regulator can also be used in this mode. This requires a clock voltage swing which is in excess of  $V_z$ . A current limit for the zener is needed, either built into the clock generator or a resistor can be used from the CLK pin to the  $V^+$  pin.

<sup>(1)</sup> Internal zener diodes (6.3 to 8.5V) are connected from V+ to GND and V<sub>CC</sub> to GND. The zener at V+ can operate as a shunt regulator and is connected to  $V_{CC}$  via a conventional diode. Since the zener voltage equals the A/D's breakdown voltage, the diode insures that V<sub>CC</sub> will be below breakdown when the device is powered from V+. Functionality is therefore ensured for V+ operation even though the resultant voltage at  $V_{CC}$  may exceed the specified Absolute Max of 6.5V. It is recommended that a resistor be used to limit the max current into V+. (See [Figure](#page-17-0) 24 in Functional Description)



**APPLICATIONS**

<span id="page-18-2"></span><span id="page-18-0"></span>





**Figure 25. Operating with a Temperature Figure 26. Generating VCC from the Converter**

<span id="page-18-3"></span><span id="page-18-1"></span>



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### **Cop Coding Example**



## **8048 Coding Example**









\*Pinouts shown for ADC0838-N. For all other products tie to pin functions as shown.





**Figure 31. Low-Cost Remote Temperature Sensor**



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**Figure 34. Span Adjust: 0V≤VIN≤3V**







**Figure 35. Zero-Shift and Span Adjust: 2V ≤ VIN ≤ 5V**



**Figure 36. Obtaining Higher Resolution - 9-Bit A/D**



Controller performs a routine to determine which input polarity (9-bit example) or which channel pair (10-bit example) provides a non-zero output code. This information provides the extra bits.



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DO = all 1s if  $+V_{IN}$  >  $-V_{IN}$ DO = all 0s if  $+V_{IN} < -V_{IN}$ 

**Figure 39. High Accuracy Comparators**





•Uses one more wire than load cell itself

•Two mini-DIPs could be mounted inside load cell for digital output transducer •Electronic offset and gain trims relax mechanical specs for gauge factor and offset •Low level cell output is converted immediately for high noise immunity





•All power supplied by loop •1500V isolation at output





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•No power required remotely

•1500V isolation







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**Figure 43. Two Wire Interface for 8 Channels**



<span id="page-27-0"></span>SNAS531B –AUGUST 1999–REVISED MARCH 2013 **[www.ti.com](http://www.ti.com)**



· Simpler version of 8-channel 100  $\mu$ S  $\begin{array}{c} \n 40 \text{ kHz} \\ \n 7 & \text{L} \\ \n 1 & \text{L} \\ \n \end{array}$ ·  $\overline{\text{CS}}$  derived from long CLK pulse m

**Figure 44. Two Wire 1-Channels Interface**



### **REVISION HISTORY**





## **PACKAGING INFORMATION**







**(1)** The marketing status values are defined as follows:

**ACTIVE:** Product device recommended for new designs.

**LIFEBUY:** TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

**NRND:** Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

**(2)** Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check<http://www.ti.com/productcontent>for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

**(3)** MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

**(4)** There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

**(5)** Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

<sup>(6)</sup> Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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# **PACKAGE MATERIALS INFORMATION**

Texas<br>Instruments

## **TAPE AND REEL INFORMATION**





# **QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE**





**TEXAS**<br>INSTRUMENTS

# **PACKAGE MATERIALS INFORMATION**

www.ti.com 5-Dec-2014



\*All dimensions are nominal



 $P (R-PDIP-T8)$ 

PLASTIC DUAL-IN-LINE PACKAGE



- B. This drawing is subject to change without notice.
- C. Falls within JEDEC MS-001 variation BA.



# **MECHANICAL DATA**

# NFF0014A





# **MECHANICAL DATA**

# N0020A NFH0020A





DW (R-PDSO-G20)

PLASTIC SMALL OUTLINE



NOTES: A. All linear dimensions are in inches (millimeters). Dimensioning and tolerancing per ASME Y14.5M-1994.

B. This drawing is subject to change without notice.

C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).

D. Falls within JEDEC MS-013 variation AC.







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